



SIMOTION Drive-based Control Unit D410-2 DP; programmable single-axis motion controller with multi-axis option; interfaces: 5 DI, 8 DI/DO, 3 F-DI, 1 F-DO, 1 AI, 1 encoder, 1 DRIVE-CLiQ, 2 PROFIBUS, 1 ethernet

|                                      |   |
|--------------------------------------|---|
| product brand name                   | SIMOTION                                  |
| product type designation             | D410-2 DP                                 |
| Version of the motion control system | Single-axis system with multi-axis option |

### PLC and motion control performance

|                                  |  |
|----------------------------------|--|
| number of axes / maximum         | 8  |
| Minimum PROFIBUS cycle clock     | 1 ms   |
| Minimum interpolator cycle clock | 0.5 ms   |
| Minimum servo cycle clock        | 0.5 ms   |
| • note                           | 1 ms when using the TO axis and the integrated closed-loop drive control |

### Integrated drive control / header

|   |   |
|---|---|
| Maximum number of axes for integrated drive control |   |
| • servo   | 1   |
| • vector  | 1   |
| • V/f   | 1   |
| • note  | Alternative control modes; drive control based on SINAMICS S120 CU310-2, firmware version V4.x/V5.x |

### Memory

|  |           |
|--|-----------|
| RAM (work memory)                                | 122 Mbyte |
| Additional RAM work memory for Java applications | 20 Mbyte  |
| RAM disk (load memory)                           | 60 Mbyte  |
| Retentive memory                                 | 108 kbyte |
| Persistent memory (user data on CF)              | 1.5 Gbyte |

### Communication

|                       |   |
|-----------------------|---|
| Interfaces            |   |
| • DRIVE-CLiQ          | 1   |
| • Industrial Ethernet | 1   |
| • PROFIBUS            | 2   |
| — note                | Equidistant and isochronous; Can be configured as master or slave |
| • PROFINET            | 0   |

### General technical data

|                            |  |
|----------------------------|--|
| Fan                        | Integrated   |
| DC supply voltage          |  |
| • rated value              | 24 V   |
| • minimum                  | 20.4 V   |
| • maximum                  | 28.8 V   |
| consumed current / typical | 800 mA   |
| • note                     | with no load on inputs/outputs, no 24 V supply via DRIVE-CLiQ and PROFIBUS interface |
| Making current, typ.       | 3 A  |
| Power loss, typ.           | 20 W   |

|  |  |
|--|--|
| Ambient temperature, during  |  |
| <ul style="list-style-type: none"> <li>• long-term storage</li> <li>• transport</li> <li>• operation</li> <li>— note</li> </ul>  | -25 ... +55 °C<br>-40 ... +70 °C<br>0 ... 55 °C<br>Maximum installation altitude 4000 m (13124 ft) above sea level. Above an altitude of 2000 m (6562 ft), the maximum ambient temperature decreases by 7 °C (12.6 °F) per 1000 m (3281 ft). |
| Relative humidity  |  |
| <ul style="list-style-type: none"> <li>• during operation</li> <li>• without condensation, tested acc. to IEC 60068-2-38</li> </ul>  | 5 ... 95 %<br>Wert fehlt   |
| Air pressure   | 620 ... 1 060 hPa  |
| Degree of protection   | IP20 / UL open type  |
| height   | 186.8 mm   |
| width  | 73 mm  |
| <ul style="list-style-type: none"> <li>• depth</li> </ul>  | 74.4 mm  |
| net weight   | 830 g  |
| <b>Digital inputs / header</b>   |  |
| number of digital inputs   | 11   |
| Digital inputs / note  | of which: 5 DI and 3 F-DI (= 6 DI)   |
| DC input voltage   |  |
| <ul style="list-style-type: none"> <li>• rated value</li> <li>• for signal "1"</li> <li>• for signal "0"</li> </ul>  | 24 V<br>15 ... 30 V<br>-3 ... +5 V   |
| Electrical isolation   | Yes  |
| Current consumption for "1" signal level, typ.   | 3.5 mA   |
| Input delay time for   |  |
| <ul style="list-style-type: none"> <li>• signal "0" → "1", typ.</li> <li>• signal "1" → "0", typ.</li> </ul>   | 50 µs<br>150 µs  |
| <b>Digital inputs/outputs / header</b>   |  |
| Number of digital I/Os   | 8  |
| Parameterization possibility of the digital I/Os   | can be parameterized - as DI - as DO - as probe input (max. 8) - as cam output (max. 8)  |
| <b>If used as an input / header</b>  |  |
| DC input voltage   |  |
| <ul style="list-style-type: none"> <li>• rated value</li> <li>• for signal "1"</li> <li>• for signal "0"</li> </ul>  | 24 V<br>15 ... 30 V<br>-3 ... +5 V   |
| Electrical isolation   | No   |
| Current consumption for "1" signal level, typ.   | 3.5 mA   |
| Input delay time for   |  |
| <ul style="list-style-type: none"> <li>• signal "0" → "1", typ.</li> <li>• signal "1" → "0", typ.</li> </ul>   | 5 µs<br>50 µs  |
| Measuring input / reproducibility  | 5 µs   |
| <ul style="list-style-type: none"> <li>• note</li> </ul>   | typical value  |
| Measuring input / resolution   | 1 µs   |
| <b>If used as an output / header</b>   |  |
| Load voltage   |  |
| <ul style="list-style-type: none"> <li>• rated value</li> <li>• minimum</li> <li>• maximum</li> </ul>  | 24 V<br>20.4 V<br>28.8 V   |
| Electrical isolation   | No   |
| Current carrying capacity for each output, max.  | 500 mA   |
| Leakage current, max.  | 2 mA   |
| Output delay for   |  |
| <ul style="list-style-type: none"> <li>• signal "0" → "1", typ.</li> <li>• signal "0" → "1", max.</li> <li>• signal "1" → "0", typ.</li> <li>• signal "1" → "0", max.</li> <li>— note</li> </ul> | 150 µs<br>400 µs<br>75 µs<br>100 µs<br>Data for Vcc = 24 V; load 48 Ohm; "1" = 90 % VOut, "0" = 10 % VOut  |
| Cam output   |  |
| <ul style="list-style-type: none"> <li>• reproducibility</li> <li>— note</li> </ul>  | 125 µs<br>typical value  |

|   |   |
|---|---|
| <ul style="list-style-type: none"> <li>• resolution</li> <li>— note</li> </ul>  | 125 µs<br>typical value   |
| Switching frequency of the outputs for  |   |
| <ul style="list-style-type: none"> <li>• resistive load, max.</li> <li>• inductive load, max.</li> <li>• lamp load, max.</li> </ul>   | 100 Hz<br>0.5 Hz<br>10 Hz   |
| Short-circuit protection  | Yes   |
| <b>Digital outputs / header</b>   |   |
| Number of digital outputs   | 1   |
| Parameterization possibility of the digital outputs   | can be parameterized as F-DO or DO  |
| Load voltage  |   |
| <ul style="list-style-type: none"> <li>• rated value</li> <li>• minimum</li> <li>• maximum</li> </ul>   | 24 V<br>20.4 V<br>28.8 V  |
| Electrical isolation  | Yes   |
| Current carrying capacity for each output, max.   | 500 mA  |
| Leakage current, max.   | 2 mA  |
| Output delay for  |   |
| <ul style="list-style-type: none"> <li>• signal "0" → "1", typ.</li> <li>• signal "0" → "1", max.</li> <li>• signal "1" → "0", typ.</li> <li>• signal "1" → "0", max.</li> <li>— note</li> </ul>  | 150 µs<br>400 µs<br>75 µs<br>100 µs<br>Data for Vcc = 24 V; load 48 Ohm; "1" = 90 % VOut, "0" = 10 % VOut   |
| Short-circuit protection  | Yes   |
| <b>Analog inputs / header</b>   |   |
| number of analog inputs   | 1   |
| <b>If used as an voltage input / header</b>   |   |
| Input voltage   | -10 ... +10 V   |
| Resolution  | 12 bit  |
| <ul style="list-style-type: none"> <li>• note</li> </ul>  | +sign   |
| Input resistance (Ri)   | 100 kΩ  |
| <b>If used as an current input / header</b>   |   |
| Input current   | -20 ... +20 mA  |
| Resolution  | 11 bit  |
| <ul style="list-style-type: none"> <li>• Note</li> </ul>  | + sign  |
| Input resistance (Ri)   | 250 Ω   |
| <b>Onboard encoder interface / header</b>   |   |
| Encoder interface   | optional incremental encoder TTL, incremental encoder HTL or absolute encoder SSI without incremental signals TTL/HTL   |
| Encoder supply for  |   |
| <ul style="list-style-type: none"> <li>• 24 VDC</li> <li>• 5 VDC</li> </ul>   | 0.35 A<br>0.35 A  |
| Limiting frequency, max.  | 500 kHz   |
| SSI baud rate   | 100 ... 1 000   |
| Resolution of absolute position SSI   | 30 bit  |
| Cable length for  |   |
| <ul style="list-style-type: none"> <li>• TTL incremental encoder, max.</li> <li>• HTL incremental encoder for <ul style="list-style-type: none"> <li>— unipolar signals, max.</li> <li>— bipolar signals, max.</li> <li>— note</li> </ul> </li> <li>• SSI absolute encoder, max.</li> <li>— note</li> </ul> | 100 m<br>100 m<br>300 m<br>TTL only bipolar signals; for bipolar signals, the signal lines must be twisted in pairs and shielded<br>100 m<br>max. cable length depends on the baud rate |
| <b>Additional technical data</b>  |   |
| design of the sensor / to detect the ambient temperature / connectable  | KTY84-130, PT1000 or PTC  |
| Back-up of non-volatile data  |   |
| <ul style="list-style-type: none"> <li>• of retentive data</li> <li>• of real-time clock, min.</li> <li>• note</li> </ul>   | unlimited buffer duration<br>5 d<br>Data buffering is maintenance-free  |
| Approvals   |   |
| <ul style="list-style-type: none"> <li>• USA</li> </ul>   | cULus   |

- Canada
- Australia
- Korea
- Russia, Belarus and Kazakhstan

cULus  
RCM (formerly C-Tick)  
KCC  
EAC

